

#### **Dual 1-of-4 Decoder / Demultiplexer in bare die form**

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#### Description

The 54AC139 is fabricated using a 1.5µm 5V advanced CMOS process and has the same high speed performance of LSTTL combined with CMOS low power consumption. This device consists of x2 independent 1–of–4 decoders, each decoding a 2 bit address to 1–of–4 active–low outputs. Active–low Selects facilitate the demultiplexing and cascading functions. The demultiplexing function is executed by using the Address inputs to select the desired device output and utilizing the Select as a data input. Inputs accept standard CMOS outputs or LSTTL outputs using pull-up resistors.

#### **Ordering Information**

The following part suffixes apply:

- No suffix MIL-STD-883 /2010B Visual Inspection
- "H" MIL-STD-883 /2010B Visual Inspection+ MIL-PRF-38534 Class H LAT
- "K" MIL-STD-883 /2010A Visual Inspection (Space)
   + MIL-PRF-38534 Class K LAT

LAT = Lot Acceptance Test.

For further information on LAT process flows see below.

www.siliconsupplies.com\quality\bare-die-lot-qualification

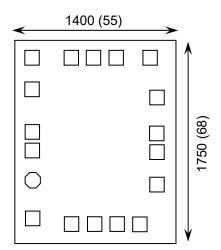
#### Supply Formats:

- Default Die in Waffle Pack (100 per tray capacity)
- Sawn Wafer on Tape On request
- Unsawn Wafer On request
- Die Thickness <> 350µm(14 Mils) On request
- Assembled into Ceramic Package On request

#### Features:

- Outputs Sink/Source 24mA
- Low Input Current: 1µA
- Outputs directly interface CMOS, NMOS and TTL
- Operating Voltage Range: 2V to 6V
- CMOS High Noise Immunity
- Function compatible with 54LS139
- Full Military Temperature Range.

#### Die Dimensions in µm (mils)



### **Mechanical Specification**

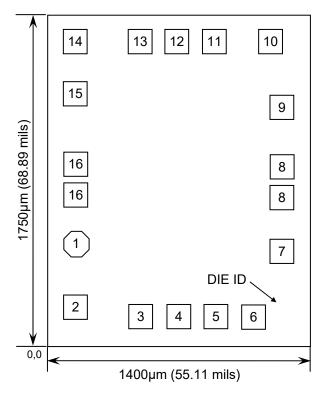
Die Size (Unsawn)	1400 x 1750 55 x 68	μm mils	
Minimum Bond Pad Size	120 x 120 4.72 x 4.72	µm mils	
Die Thickness	350 (±20) 13.78 (±0.79)	μm mils	
Top Metal Composition	Al 1%Si 1.1μ	m	
Back Metal Composition	al Composition N/A – Bare Si		



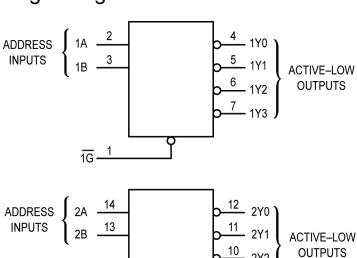


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## Pad Layout and Functions



### Logic Diagram



PAD	FUNCTION	COORDINATES (mm)			
PAD	I AD I GROTION	X	Υ		
1	1G	0.100	0.487		
2	1A	0.100	0.150		
3	1B	0.440	0.100		
4	1Y0	0.640	0.100		
5	1Y1	0.835	0.100		
6	1Y2	1.030	0.100		
7	1Y3	1.180	0.440		
8	GND	1.180	0.720		
8	GND	1.180	0.880		
9	2Y3	1.180	1.190		
10	2Y2	1.120	1.530		
11	2Y1	0.826	1.530		
12	2Y0	0.630	1.530		
13	2B	0.436	1.530		
14	2A	0.100	1.530		
15	2G	0.100	1.260		
16	V <sub>CC</sub>	0.100	0.895		
16	V <sub>CC</sub>	0.100	0.735		
CONNECT CHIP BACK TO V <sub>CC</sub> OR FLOAT					

### **Truth Table**

IN	OUTPUTS			3		
G	В	Α	Y0	Y1	Y2	Y3
Н	Χ	Χ	Н	Н	Н	Н
L	L	L	L	Н	Н	Н
L	L	Н	Н	L	Н	Н
L	Н	L	Н	Н	L	Н
L	Н	Н	Н	Н	Н	L

X = don't care



2G \_\_\_\_\_15

Pad 16 = V<sub>CC</sub>

Pad 8 = GND



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## **Pad Description**

ADDRESS INPUTS 1A, 1B, 2A, 2B

(Pads 2, 3, 14, 13)

When the respective 1-of-4 decoder is enabled these inputs determine which of its four active-low outputs is selected.

#### **CONTROL INPUTS**

1G, 2G

(Pads 1, 15)

Active—low select inputs. For a low level on this input, the outputs for that particular decoder follow the Address inputs. A high level on this input forces all outputs to a high level.

#### **OUTPUTS**

1Y0, 1Y1, 1Y2, 1Y3, 2Y0, 2Y1, 2Y2, 2Y3

(Pads 4-7, 12, 11, 10, 9)

Active—low outputs. These outputs assume a low level when addressed and the appropriate Select input is active. These outputs remain high when not addressed or the appropriate Select input is inactive.

### Absolute Maximum Ratings<sup>1</sup>

PARAMETER	SYMBOL	VALUE	UNIT
DC Supply Voltage (Referenced to GND)	V <sub>CC</sub>	-0.5 to +7.0	V
DC Input Voltage (Referenced to GND)	V <sub>IN</sub>	-0.5 to V <sub>CC</sub> +0.5	V
DC Output Voltage (Referenced to GND)	V <sub>OUT</sub>	-0.5 to V <sub>CC</sub> +0.5	V
DC Input Current, per pin	I <sub>IN</sub>	±20	mA
DC Output Current, per pin	I <sub>OUT</sub>	±50	mA
DC V <sub>CC</sub> or GND Current, per pin	I <sub>cc</sub>	±50	mA
Power Dissipation in Still Air <sup>2</sup>	P <sub>D</sub>	750	mW
Storage Temperature Range	T <sub>STG</sub>	-65 to 150	°C

<sup>1.</sup> Operation above the absolute maximum rating may cause device failure. Operation at the absolute maximum ratings, for extended periods, may reduce device reliability. 2. Measured in plastic DIP package, results in die form are dependent on die attach and assembly method.

## Recommended Operating Conditions<sup>3</sup> (Voltages referenced to GND)

PARAMETER	SYMBOL	MIN	MAX	UNITS	
DC Supply Voltage		V <sub>CC</sub>	2	6	V
DC Input or Output Voltage		$V_{IN}$ , $V_{OUT}$	0	V <sub>CC</sub>	V
Operating Temperature Range		T <sub>J</sub>	-55	+125	°C
Output Current – High		I <sub>OH</sub>	-	-24	mA
Output Current – Low		I <sub>OL</sub>	-	24	mA
Input Disc and Fall Time	V <sub>CC</sub> = 3.0V		0	150	
Input Rise and Fall Time (V <sub>IN</sub> from 30% to 70%)	$V_{CC} = 4.5V$	t <sub>r</sub> , t <sub>f</sub>	0	40	ns/V
(1)(11011110070101070)	V <sub>CC</sub> = 5.5V		0	24	

<sup>3.</sup> This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high-impedance circuit. For proper operation,  $V_{IN}$  and  $V_{OUT}$  should be constrained to the range GND  $\leq$  ( $V_{IN}$  or  $V_{OUT}$ )  $\leq$   $V_{CC}$ . Unused inputs must always be tied to an appropriate logic voltage level (e.g., either GND or  $V_{CC}$ ). Unused outputs must be left open.





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## DC Electrical Characteristics (Voltages Referenced to GND)

PARAMETER	SYMBOL	V <sub>cc</sub>	CONDITIONS	LIMITS			
			CONDITIONS	25°C	85°C	FULL RANGE⁴	UNITS
Minimum High-Level Input Voltage	V <sub>IH</sub>	3.0V	$V_{OUT} = 0.1V \text{ or}$ $V_{CC} - 0.1V$ $\left  I_{OUT} \right  \le 20 \mu A$	2.1	2.1	2.1	V
		4.5V		3.15	3.15	3.15	
input voltage		5.5V		3.85	3.85	3.85	
Massimas para Lavral		3.0V	$V_{OUT} = 0.1V$ or $V_{CC} = 0.1V$	0.9	0.9	0.9	V
Maximum Low-Level Input Voltage	V <sub>IL</sub>	4.5V		1.35	1.35	1.35	
mput voltage		5.5V	I <sub>OUT</sub>   ≤ 20µA	1.65	1.65	1.65	
		3.0V		2.9	2.9	2.9	
		4.5V	$I_{OUT} = -50\mu A$	4.4	4.4	4.4	
		5.5V		5.4	5.4	5.4	
Minimum High-Level	.,,	3.0V	$V_{IN} = V_{IL} \text{ or } V_{IH}$ $I_{OH} = -12 \text{ mA}$	2.56	2.46	2.40	V
Output Voltage	V <sub>OH</sub>	4.5V	$V_{IN} = V_{IL} \text{ or } V_{IH}$ $I_{OH} = -24 \text{ mA}^5$	3.86	3.76	3.70	
		5.5V	$V_{IN} = V_{IL} \text{ or } V_{IH}$ $I_{OH} = -24 \text{mA}^5$	4.86	4.76	4.70	
		5.5V	$V_{IN} = V_{IL} \text{ or } V_{IH}$ $I_{OH} = -50 \text{mA}^{6}$	-	-	3.85	
	3.0V 4.5V 5.5V 3.0V 4.5V 5.5V	3.0V	Ι <sub>ουτ</sub> = 50μΑ	0.1	0.1	0.1	
		4.5V		0.1	0.1	0.1	
		5.5V		0.1	0.1	0.1	
Maximum Low-Level		3.0V	$V_{IN} = V_{IH} \text{ or } V_{IL}$ $ I_{OUT}  \le 12\text{mA}$	0.36	0.44	0.5	
Output Voltage		4.5V	$V_{IN} = V_{IH} \text{ or } V_{IL}$ $\left  I_{OUT} \right  \le 24 \text{mA}^5$	0.36	0.44	0.5	V
		5.5V	$V_{IN} = V_{IH} \text{ or } V_{IL}$ $\left  I_{OUT} \right  \le 24 \text{mA}^5$	0.36	0.44	0.5	
		5.5V	$V_{IN} = V_{IH} \text{ or } V_{IL}$ $\left  I_{OUT} \right  50 \text{mA}^6$	-	-	1.65	
Maximum Input Leakage Current	I <sub>IN</sub>	5.5V	$V_{IN} = V_{CC}$ or GND	±0.1	±1.0	±1.0	μA
Minimum Dynamic	I <sub>OLD</sub>	5.5V	$V_{OLD} = 1.65V Max$	-	75	50	mA
Output Current <sup>7</sup>	I <sub>OHD</sub>	5.5V	V <sub>OHD</sub> = 3.85V Min	-	-75	-50	IIIA
Maximum Quiescent Supply Current	I <sub>CC</sub>	5.5V	$V_{IN} = V_{CC}$ or GND $I_{OUT} = 0\mu A$	8	80	160	μA

<sup>4.</sup>  $-55^{\circ}$ C  $\leq T_{J} \leq +125^{\circ}$ C 5. All outputs loaded; thresholds on input associated with output under test. 6. Test time 1sec max, measurement made by forcing indicated current and measuring voltage to minimize power dissipation. Test verifies a minimum 75 $\Omega$  transmission-line drive capability at 125°C 7. Maximum test duration 2ms, one output loaded at a time





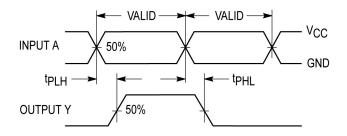
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# AC Electrical Characteristics<sup>8</sup> (V<sub>CC</sub> 3.3V ±0.3V, V<sub>CC</sub> 5V ±0.3V)

PARAMETER	SYMBOL	V <sub>cc</sub>	CONDITIONS		UNITS							
		- 00		25°C	85°C	FULL RANGE⁴						
Maximum Propagation Delay,	t <sub>PLH,</sub>	3.3V	C <sub>L</sub> = 50pF,	11.5	13	14.7	ns					
		5.0V	$t_r = t_f = 3$ ns	8.5	9.5	10.5						
A or B to Y (Figure 1,3)	t <sub>PHL</sub>	3.3V	$C_L = 50 \text{pF},$ $t_r = t_f = 3 \text{ns}$	10	11	14.7	ns					
( 3 , ,		5.0V		7.5	8.5	10.5						
Maximum Propagation Delay, G to Y (Figure 2,3)	t <sub>PLH,</sub>	3.3V	$C_L = 50 pF,$ $t_r = t_f = 3 ns$	12	13	14.7	ns					
		5.0V		8.5	10	10.5						
	t <sub>PHL</sub>	3.3V	C <sub>L</sub> = 50pF,	10	11	14.7						
		5.0V	$t_r = t_f = 3$ ns	7.5	8.5	10.5	113					
Maximum Input Capacitance	C <sub>IN</sub>	-	-	4.5	4.5	4.5	pF					
Power Dissipation	cance $C_{PD}$ - $V_{PD}$ - $V_{PD}$ - $V_{PD}$	-	-				_	T <sub>1</sub> = 25°C.	TYPICAL		CAL	
Capacitance (Per Decoder) <sup>9</sup>						4	0	pF				

- 8. Not production tested in die form, characterized by chip design and tested in package.
- **9.** Used to determine the no-load dynamic power consumption:  $P_D = C_{PD} V_{CC}^2 f + I_{CC} V_{CC}$ .

### **Switching Waveforms**





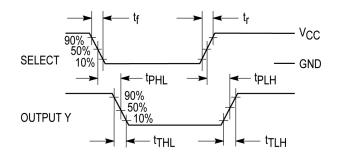
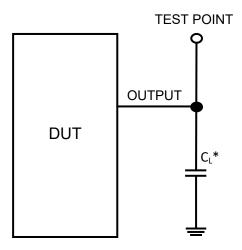


Figure 2 – Propagation Delay & Timing , Input Select to Output





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<sup>\*</sup> Includes all probe and jig capacitance

Figure 3 - Test Circuit

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