

Single-supply linear-output temperature sensor in bare die form

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Description

The LM135 precision linear-output temperature sensor is designed for simple calibration and ease of use. Output is derived from an integrated 2-terminal Zener with a breakdown voltage directly proportional to absolute temperature at $10\text{mV/}^\circ\text{K}$. Calibrated at $+25^\circ\text{C}$, the LM135 has an accuracy of 0.5°C over a wide -55°C to 150°C temperature range. With less than 1Ω dynamic impedance, performance is consistent across a current range of $450\mu\text{A}$ to 5mA. The device suits use as a general purpose sensor where its small size, low impedance and linear output enables simple circuit integration.

Ordering Information

The following part suffixes apply:

- No suffix MIL-STD-883 /2010B Visual Inspection
- "H" MIL-STD-883 /2010B Visual Inspection+ MIL-PRF-38534 Class H LAT
- "K" MIL-STD-883 /2010A Visual Inspection (space)
 + MIL-PRF-38534 Class K (A)

LAT = Lot Acceptance Test.

For further information on LAT process flows see below.

www.siliconsupplies.com\quality\bare-die-lot-qualification

For a higher electrical rade version of this product see <u>LM135A</u>

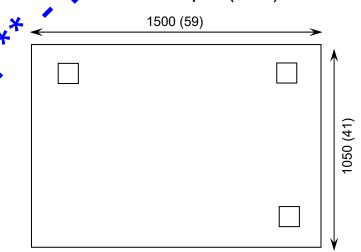
Supply Formats:

- Default Die in Waffle Pack (400 per tray capacity)
- Sawn Wafer on Tape On request
- Unsawn Wafer On request
- Die Thickness <> 350µm(14 Mils) On request
- Assembled into Hermetic Package On request

Features:

- Wide temperature range: -55 to +15 °C
- 0.5% typical accuracy at 25°C
- Single-point calibration for kigh precision
- Operates from 450µA to 5mx
- <1Ω dynamic impędance
- Linear output
- Intermitten operation capability at 200°C
- Small size wigh integration

Die Dimensions in µm (mils)



Mechanical Specification

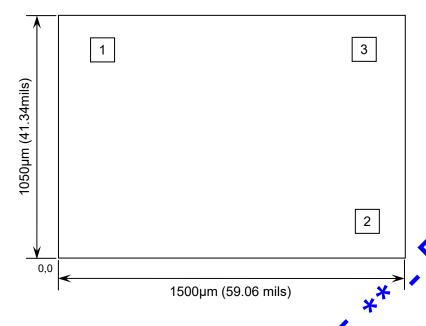
Die Size (Unsawn)	1500 x 1050 59 x 41	µm mils
Minimum Bond Pad Size	104 x 104 4.09 x 4.09	μm mils
Die Thickness	350 (±20) 13.78 (±0.79)	μm mils
Top Metal Composition	Al 1%Si 1.1µm	
Back Metal Composition	N/A – Bare Si	





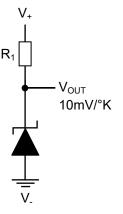
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Pad Layout and Functions



PAD	FUNCTION	COORDIN	Δ 1 ፫ ۶ (μm)	
ואט	TONOTION	Х	Υ	
1	V+	13.1	848	
2	V-	12o l	103	
3	ADJ	1268	848	
CONNECT CHIP BACK TO V- OR FLOAT				

Simplified Schematic



Calibration methodology and schematic

The LM135 response is proportional to absolute temperature with the extrapolated output of sensor going to 0V at 1 K (-273.15°C). Errors in output voltage versus temperature are only slope. Thus a calibration of the slope at one temperature corrects errors at an temperatures. The circuit output (calibrated or not) is given by the equation:

$$VOUT_T + VOUT_{To} \times \frac{T}{T_o}$$

Where:

- T is the unknown temperature
- To is the reference temperature (in °K).

Nominally, the output is calibrated at 10mV/°K.

Application Note:

Self-heating can decrease accuracy; LM135 should be operated at low current but sufficient enough to drive the sensor and calibration circuit to the maximum operating temperature. If used in surroundings where the thermal resistance is constant, the errors due to self-heating can be externally calibrated. This is possible if the circuit is biased with a temperature stable current. Heating will then be proportional to Zener voltage and therefore temperature. In this way, the error due to self-heating is proportional to the absolute temperature as scale factor errors.



V_{OUT} 10mV/°K

10kΩ*

* Calibrated for

2.982V at 25°C



Absolute Maximum Ratings¹

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PARAMETER	SYMBOL	VALUE		UNIT
Reverse Current	I _R	15		IΛA
Forward Current	I _F	10		'nA
Operating Temperature	T	Continuous	-55 to +150	°C
Operating Temperature	I OPER	Intermittent	-55 to +200	V
Storage Temperature	T _{STG}	-65 to +150		°C

^{1.} Operation above the absolute maximum rating may cause device failure. Operation at the absolute maximum ratings, for extended periods, may reduce device reliability.

Recommended Operating Conditions

PARA	METER	SYMBOL	MIN	MAX	UNITS
Temperature	Continuous	т.	-55	150	°C
remperature	Intermittent	I A	-55	200	
Forward Current		I _F	0.45	5	mA

Temperature Parameters² (T_A = 25°C unless therwise specified)

PARAMETER SYMBOL CONDITIONS		LIMITS			UNITS	
IANAMETER	FARAMETER STWIDGE CONDITIONS	CONDITIONS	MIN	TYP	MAX	ONITS
Output Voltage	V _{OUT}	$T_J = 25$ °C, $V_R = 1$ mA	2.95	2.98	3.01	V
Un-calibrated	ΔT ₁	$T_A = 25^{\circ}C$, $I_R = 1mA$	-	1	3	°C
Temperature Error	ΔT_2	-55°C< T _A ≤ 150°C,I _R = 1mA	-	2	5	°C
25°C Calibrated	ΔT_3	-56°C3 1 _A ≤ +150°C,I _R = 1mA	-	0.5	1.5	°C
Temperature Error	ΔT_4	200°C, Intermittent	-	2	-	°C
Non-linearity	ΔT_5	-5 ¹ °C≤ T _A ≤ +150°C,I _R = 1mA	-	0.3	1	°C

Electrical Parameters² (T_A = 25°C unless otherwise specified)

PARAMETER	SYMBOL	SYMBOL CONDITIONS	LIMITS			UNITS
	4 I WIBOL		MIN	TYP	MAX	UNITS
Output voltage change with our ent	ΔV _{OUT}	450μA ≤ I _R ≤ 5mA, Constant temperature	-	2.5	10	mV
Dynamic mredance	ΔR_1	$T_J = 25^{\circ}C, I_R = 1mA$	-	0.5	-	Ω
Temperature coefficient of output voltage	тс	$T_J = 25^{\circ}C, I_R = 1mA$	-	+10	-	mV/°C
		Still air	-	80	-	
Time constant	$\mid \tau_{T} \mid$	τ _T Air 0.5m/s	-	10	-	s
		Stirred oil	-	1	-	
Time stability	T _{STAB}	T _J = 125°C	-	0.2	-	°C/1000h

^{2.} Accuracy measurements are made in a well-stirred oil bath. For other conditions, self-heating must be considered.





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Typical Characteristics (T_J = 25°C unless otherwise specified)

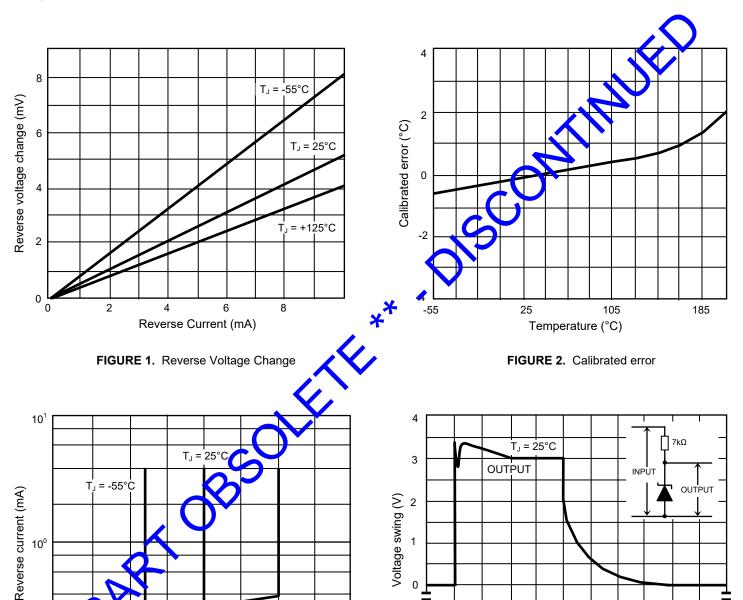


FIGURE 3. Reverse characteristics

Reverse Voltage (V)

 $T_J = +125^{\circ}C$

FIGURE 4. Response time

Time (µS)

INPUT



10

0



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Typical Characteristics (T_J = 25°C unless otherwise specified)

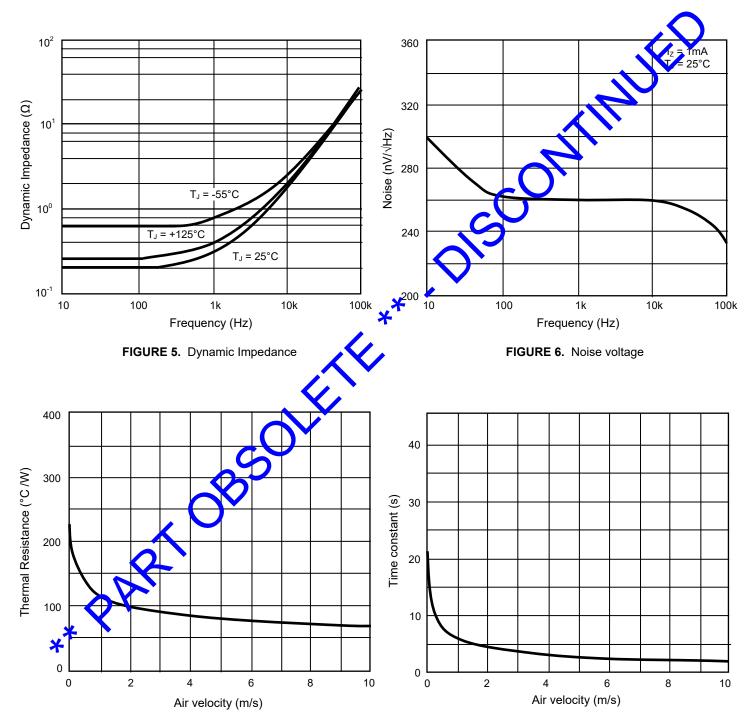


FIGURE 8. Thermal resistance, junction-to-air

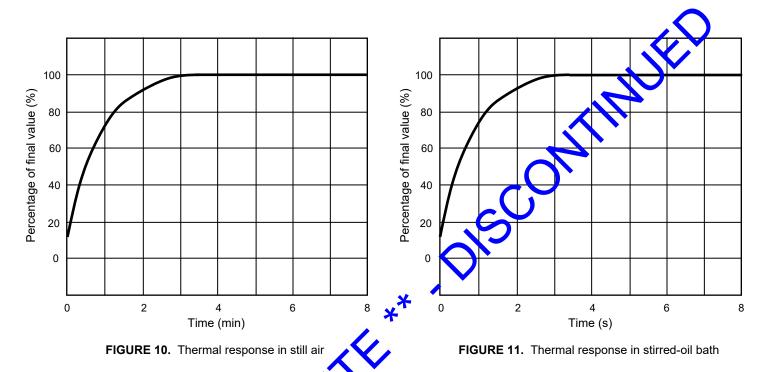
FIGURE 9. Thermal time constant





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Typical Characteristics (T_J = 25°C unless otherwise specified)



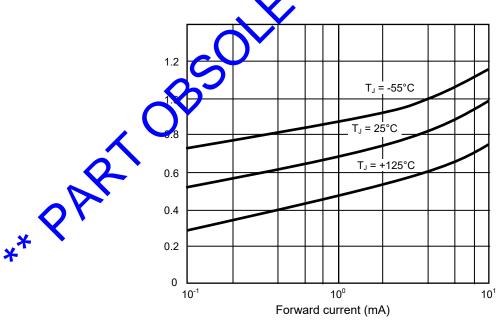


FIGURE 12. Forward characteristics





Typical Applications

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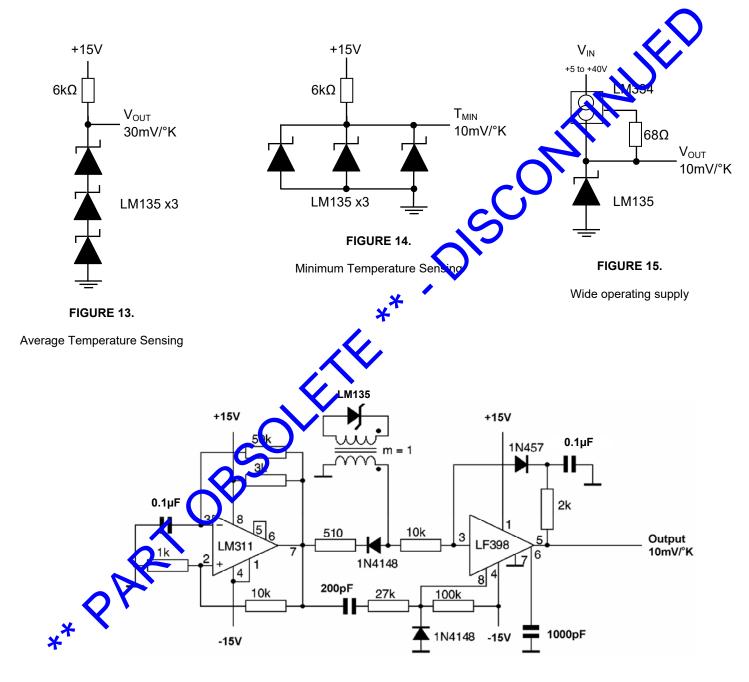


FIGURE 16.

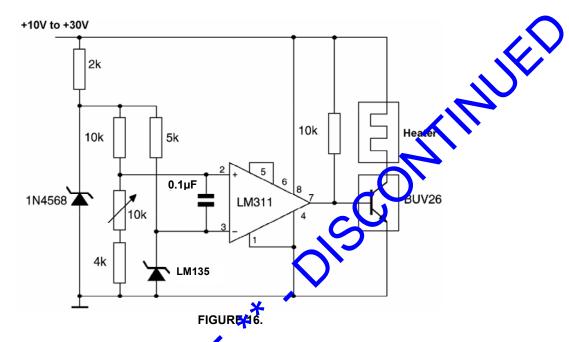
Isolated Temperature Sensor





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Typical Applications continued



Temperature Controller 1k +15V +15V +15V 200k 12k 12k 6k +15V 20k LM308 Output 10mV/°C Output LM308 10mV/°C 20k 10k LM135 -15V 180k 📥 100pF LM135 100pF 50k *Adjust for 2.7315V at output of LM308

FIGURE 17.

Centigrade Thermometer

FIGURE 18.

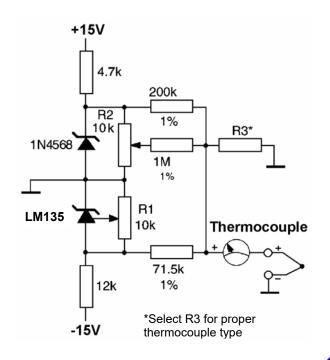
Differential Temperature Sensor





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Thermocouple compensation



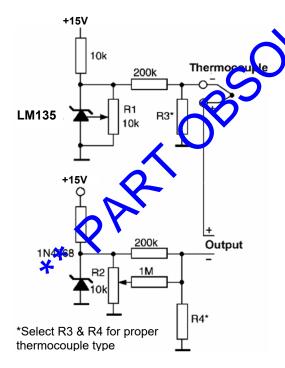
Thermocouple	R3	SEEBECK Coefficient
J	377Ω	52.3µ. //°C
Т	308Ω	42.8 JV/°C
K	293Ω	40.8μV/°C
S	45.80	6.4μV/°C

Adjustments:

- 1. Short 1N4568.
- Adjust R1 or STEBECK coefficient times ambient temperature in regrees Kelvin across R3.
- 3. Short M135 and adjust R2 for voltage across R3 corresponding to thermocouple type as below:

* J	14.32mV	K	11.17mV
T	11.9mV	S	1.768mV

FIGURE 19. Thermocouple cold junctic compensation (compensation for grounded thermocouple)



Thermocouple	R3	R4	SEEBECK Coefficient
J	1.05kΩ	365Ω	52.3µV/°C
Т	856Ω	315Ω	42.8µV/°C
K	816Ω	300Ω	40.8µV/°C
S	128Ω	46.3Ω	6.4µV/°C

Adjustments:

- 1. Adjust R1 for the voltage across R3 equal to the SEEBECK coefficient times ambient temperature in degrees Kelvin.
- 2. Adjust R2 for voltage across R4 corresponding to the thermocouple as below:

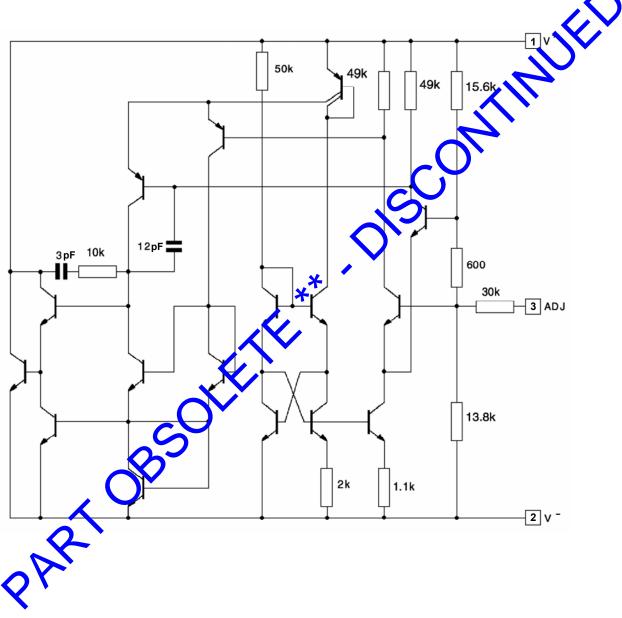
J	14.32mV	K	11.17mV
Т	11.9mV	S	1.768mV

FIGURE 20. Single power supply cold junction compensation





Circuit schematic Rev 1.1 28/04/20



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