



High Speed CMOS TTL Input – 54HCT163

Programmable 4-bit counter with synchronous reset in bare die form

Rev 1.0
06/06/19

Description

The 54HCT163 programmable synchronous 4-bit decade and binary counter is fabricated using a 2.5 μ m 5V CMOS process with the same high speed performance of LSTTL combined with CMOS low power consumption. Clock input is active on the rising edge. Both load (\overline{SPE}) and clear (\overline{MR}) inputs are active low. Presetting is synchronous on rising clock edge. Two enable inputs (TE and PE) and ripple carry output (TC) are provided to enable easy cascading of counters, facilitating simple implementation of N-bit counters without use of external gates. Device inputs directly accept LSTTL or CMOS. All inputs are protected against ESD and excess voltage transients.

Ordering Information

The following part suffixes apply:

- No suffix - MIL-STD-883 /2010B Visual Inspection
- “H” - MIL-STD-883 /2010B Visual Inspection + MIL-PRF-38534 Class H LAT
- “K” - MIL-STD-883 /2010A Visual Inspection (Space) + MIL-PRF-38534 Class K LAT

LAT = Lot Acceptance Test.

For further information on LAT process flows see below.

www.siliconsupplies.com/quality/bare-die-lot-qualification

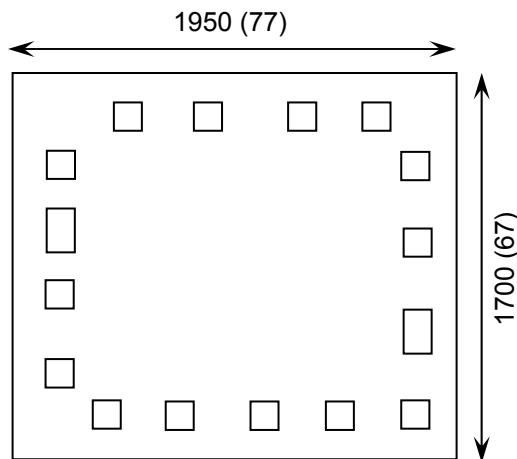
Supply Formats:

- Default - Die in Waffle Pack (100 per tray capacity)
- * Sawn Wafer on Tape – On request
- Unsawn Wafer – On request
- Die Thickness <> 350 μ m(14 Mils) – On request
- Assembled into Ceramic Package – On request

Features:

- Output Drive Capability: 10 LSTTL Loads
- Low Input Current: 1 μ A
- TTL / CMOS compatible Input Levels
- Outputs directly interface CMOS, NMOS and TTL
- Operating Voltage Range: 4.5V to 5.5V
- Function compatible with 54LS163
- Full Military Temperature Range.

Die Dimensions in μ m (mils)



Mechanical Specification

Die Size (Unsawn)	1950 x 1700 78 x 67	μ m mils
Minimum Bond Pad Size	120 x 120 4.72 x 4.72	μ m mils
Die Thickness	350 (± 20) 13.78 (± 0.79)	μ m mils
Top Metal Composition	Al 1%Si 1.1 μ m	
Back Metal Composition	N/A – Bare Si	



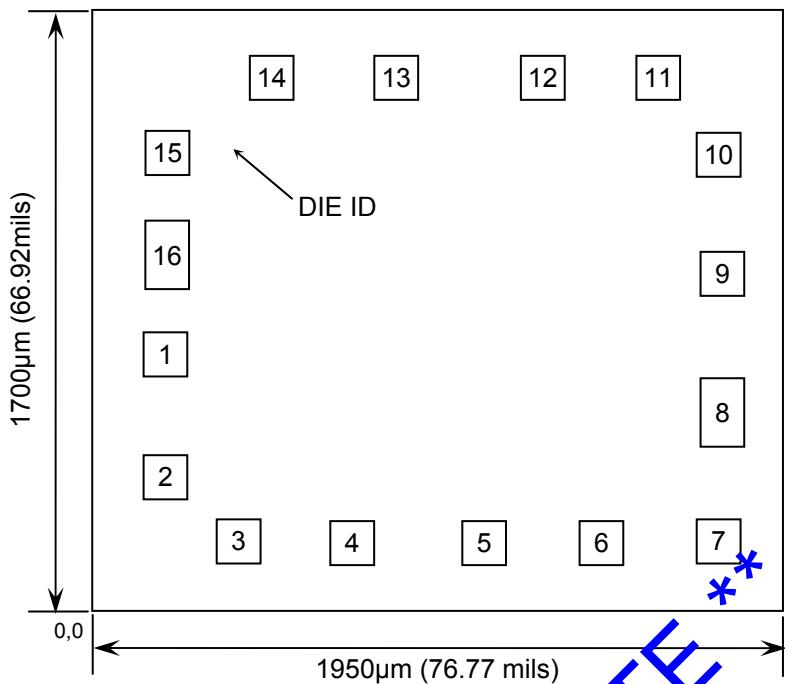


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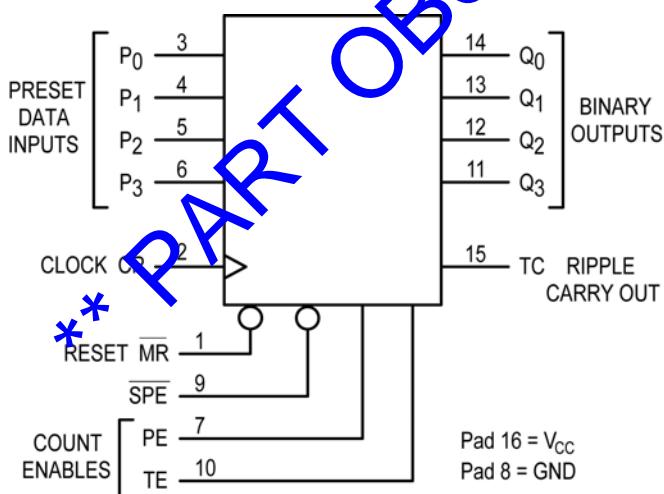
Pad Layout and Functions



PAD	FUNCTION	COORDINATES (mm)	
		X	Y
1	MR	0.145	0.655
2	CP	0.145	0.315
3	P0	0.350	0.135
4	P1	0.670	0.125
5	P2	1.045	0.125
6	P3	1.375	0.125
7	PE	1.698	0.135
8	GND	1.712	0.465
9	SPE	1.712	0.885
10	TE	1.698	1.229
11	Q3	1.533	1.441
12	Q2	1.208	1.441
13	Q1	0.795	1.441
14	Q0	0.440	1.441
15	TC	0.155	1.227
16	V _{CC}	0.155	0.910

CONNECT CHIP BACK TO V_{CC} OR FLOAT

Logic Diagram



Function Table

INPUTS					OUTPUT
CP	MR	SPE	PE	TE	Q
↑	L	X	X	X	RESET
↑	H	L	X	X	LOAD DATA
↑	H	H	H	H	COUNT
↑	H	H	L	X	NO COUNT
↑	H	H	X	L	NO COUNT



Function Description

INPUTS

Clock (CP - Pad 2)

The internal flip-flops toggle and the output count advances with the rising edge of the Clock input. In addition, control functions such as resetting and loading occur with the rising edge of the Clock Input.

Preset Data Inputs (P0, P1, P2, P3 - Pads 3, 4, 5, 6)

These are the data inputs for programmable counting. Data on these pins may be synchronously loaded into the internal flip-flops and appear at the counter outputs. P0 (Pad 3) is the least-significant bit and P3 (Pad 6) is the most-significant bit.

OUTPUTS

Q0, Q1, Q2, Q3 (Pads 14, 13, 12, 11)

These are the counter outputs. Q0 (Pad 14) is the least-significant bit and Q3 (Pad 11) is the most-significant bit.

Ripple-Carry Out (TC - Pad 15)

When the counter is in its maximum state 1111, this output goes high, providing an external look-ahead carry pulse that may be used to enable successive cascaded counters. Ripple Carry Out remains high only during the maximum count state. Logic equation for this output is:

$$\text{Ripple Carry Out (TC)} = \text{T Enable (TE)} \cdot \text{Q}0 \cdot \text{Q}1 \cdot \text{Q}2 \cdot \text{Q}3$$

CONTROL FUNCTIONS

Reset (MR – Pad 1)

A low level on Reset resets the internal flip-flops & sets the outputs (Q0 through Q3) to a low level. Reset is synchronous with the rising edge of the Clock input.

Synchronous Parallel Enable (SPE - Pad 9)

With the rising edge of the Clock, a low level on SPE loads the data from the Preset Data input pads (P0, P1, P2, P3) into the internal flip-flops and onto the output pins, Q0 through Q3. The count function is disabled as long as Load is low.

Count Enable/Disable (PE and TE - Pads 7, 10)

The device has two count-enable control pins: P Enable (PE) and T Enable (TE). The device counts when these two pads and the Data load pad are high. The logic equation is:

$$\text{Count Enable} = \text{P Enable} \cdot \text{T Enable} \cdot \text{Data Load}$$

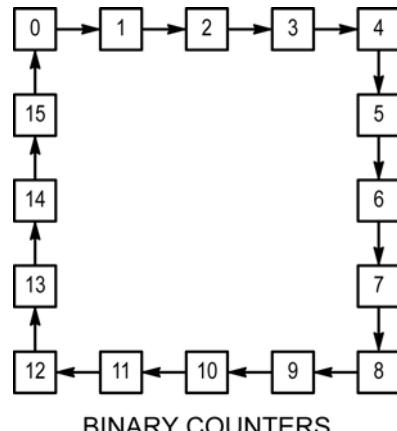
The count is either enabled or disabled by the control inputs according to Figure 1. In general, P Enable (PE) is a count-enable control: T Enable (TE) is both a count-enable and a Ripple-Carry Output control.

Count Enable / Disable truth table

CONTROL INPUTS			RESULT AT OUTPUTS	
SPE	PE	TE	Q0-Q3	TC
H	L	H	COUNT	HIGH WHEN Q0–Q3 ARE MAX
L	H	H	NO COUNT	HIGH WHEN Q0–Q3 ARE MAX
X*	L	H	NO COUNT	HIGH WHEN Q0–Q3 ARE MAX
X	X	L	NO COUNT	L

Q0 through Q3 are maximum when Q3 Q2 Q1 Q0 = 1111.

Output State Diagram





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Absolute Maximum Ratings¹

PARAMETER	SYMBOL	VALUE	UNIT
DC Supply Voltage (Referenced to GND)	V _{CC}	-0.5 to +7.0	V
DC Input Voltage (Referenced to GND)	V _{IN}	-1.5 to V _{CC} +1.5	V
DC Output Voltage (Referenced to GND)	V _{OUT}	-0.5 to V _{CC} +0.5	V
DC Input Current	I _{IN}	±20	mA
DC Output Current, per pad	I _{OUT}	±25	mA
DC Supply Current, V _{CC} or GND, per pad	I _{CC}	±50	mA
Power Dissipation in Still Air ²	P _D	750	mW
Storage Temperature Range	T _{STG}	-65 to 150	°C

1. Operation above the absolute maximum rating may cause device failure. Operation at the absolute maximum ratings, for extended periods, may reduce device reliability. 2. Measured in plastic DIP package, results in die form are dependent on die attach and assembly method.

Recommended Operating Conditions³ (Voltages referenced to GND)

PARAMETER	SYMBOL	MIN	MAX	UNITS
Supply Voltage	V _{CC}	4.5	5.5	V
DC Input or Output Voltage	V _{IN} , V _{OUT}	0	V _{CC}	V
Operating Temperature Range	T _J	*-55	+125	°C
Input Rise or Fall Times	t _r , t _f	-	500	ns

3. This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high-impedance circuit. For proper operation, V_{IN} and V_{OUT} should be constrained to the range GND ≤ (V_{IN} or V_{OUT}) ≤ V_{CC}. Unused inputs must always be tied to an appropriate logic voltage level (e.g., either GND or V_{CC}). Unused outputs must be left open.

DC Electrical Characteristics (Voltages Referenced to GND)

PARAMETER	SYMBOL	V _{CC}	CONDITIONS	LIMITS			UNITS
				25°C	85°C	FULL RANGE ⁴	
Minimum High-Level Input Voltage	V _{IH}	4.5V	V _{OUT} = 0.1V or V _{CC} - 0.1V I _{OUT} ≤ 20µA	2.0	2.0	2.0	V
		5.5V		2.0	2.0	2.0	
Maximum Low-Level Input Voltage	V _{IL}	4.5V	V _{OUT} = 0.1V I _{OUT} ≤ 20µA	0.8	0.8	0.8	V
		5.5V		0.8	0.8	0.8	
Minimum High-Level Output Voltage	V _{OH}	4.5V	V _{IN} = V _{IH} or V _{IL} I _{OUT} ≤ 20µA	4.4	4.4	4.4	V
		5.5V		5.4	5.4	5.4	
		4.5V	V _{IN} = V _{IH} or V _{IL} I _{OUT} ≤ 4.0mA	3.98	3.84	3.70	
Maximum Low-Level Output Voltage	V _{OL}	4.5V	V _{IN} = V _{IH} or V _{IL} I _{OUT} ≤ 20µA	0.1	0.1	0.1	V
		5.5V		0.1	0.1	0.1	
		4.5V	V _{IN} = V _{IH} or V _{IL} I _{OUT} ≤ 4.0mA	0.26	0.33	0.40	





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DC Electrical Characteristics Continued (Voltages Referenced to GND)

PARAMETER	SYMBOL	V _{CC}	CONDITIONS	LIMITS			UNITS
				25°C	85°C	FULL RANGE ⁴	
Maximum Input Leakage Current	I _{IN}	5.5V	V _{IN} = V _{CC} or GND	±0.1	±1.0	±1.0	µA
Maximum Quiescent Supply Leakage Current ⁵	I _{CC}	5.5V	V _{IN} = V _{CC} or GND I _{OUT} ≤ 0µA	4	40	160	µA
Additional Quiescent Supply Current ⁵	ΔI _{CC}	5.5V	V _{IN} = 2.4V, Any One Input. V _{IN} = V _{CC} or GND, Other Inputs I _{OUT} = 0µA	≥ -55°C	25°C to 125°C	2.4	mA

4. -55°C ≤ T_J ≤ +125°C 5. Total Supply Current = I_{CC} + ΣΔI_{CC}.

AC Electrical Characteristics⁶

PARAMETER	SYMBOL	V _{CC}	CONDITIONS [*]	LIMITS			UNITS
				25°C	85°C	FULL RANGE ⁴	
Maximum Clock Frequency (50% Duty Cycle) (Figure 1, 3)	f _{MAX}	5V ±10%	C _L = 50pF, Input t _r = t _f = 6ns	30	24	20	MHz
Maximum Propagation Delay, CP to Q (Figure 1, 3)	t _{PLH}	5V ±10%	C _L = 50pF, Input t _r = t _f = 6ns	20	23	28	ns
Maximum Propagation Delay, TE to TC (Figure 1, 3)	t _{PLH} , t _{PHL}	5V ±10%	C _L = 50pF, Input t _r = t _f = 6ns	16	18	20	ns
Maximum Propagation Delay, CP to TC (Figure 1, 3)	t _{PLH} , t _{PHL}	5V ±10%	C _L = 50pF, Input t _r = t _f = 6ns	21	24	28	ns
Maximum Output Transition Time, Any Output (Figure 1, 3)	t _{TLH} , t _{THL}	5V ±10%	C _L = 50pF, Input t _r = t _f = 6ns	22	25	28	ns
* Maximum Input Capacitance	C _{IN}	-	-	28	33	35	pF
Power Dissipation Capacitance Per Gate ⁶	C _{PD}	5V	T _J = 25°C	TYPICAL			pF
				60			

6. Not production tested in die form, characterized by chip design and tested in package.

7. Used to determine the no-load dynamic power consumption: P_D = C_{PD} V_{CC}²f + I_{CC} V_{CC}.





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Timing Requirements⁶

PARAMETER	SYMBOL	V _{CC}	CONDITIONS	LIMITS			UNITS
				25°C	85°C	FULL RANGE ⁵	
Minimum Setup Time, Pn to CP	t _{SU}	5V ±10%	C _L = 50pF, Input t _r = t _f = 6ns	12	18	20	ns
Minimum Setup Time, SPE to CP				12	18	20	
Minimum Setup Time, MR to CP				12	18	20	
Minimum Setup Time, TE or PE to CP				12	18	20	
Minimum Hold Time, CP to Pn	t _h	5V ±10%	C _L = 50pF, Input t _r = t _f = 6ns	3	3	3	ns
Minimum Hold Time, CP to SPE				3	3	3	
Minimum Hold Time, CP to MR				3	3	3	
Minimum Hold Time, CP to TE or PE				3	3	3	
Minimum Recovery Time, SPE Inactive to CP	t _{rec}	5V ±10%	C _L = 50pF, Input t _r = t _f = 6ns	12	17	23	ns
Minimum Pulse Width, CP	t _w	5V ±10%	C _L = 50pF, Input t _r = t _f = 6ns	12	15	18	ns
Maximum Input Rise and Fall times	t _r , t _f	5V ±10%	C _L = 50pF, Input t _r = t _f = 6ns	500	500	500	ns

Switching Waveforms

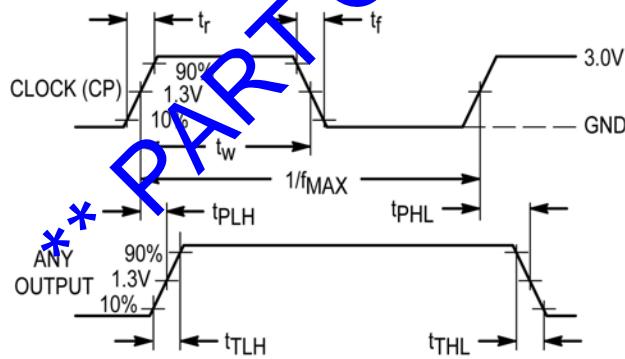


Figure 1 – Propagation Delay & Clock Timing, Clock to Output

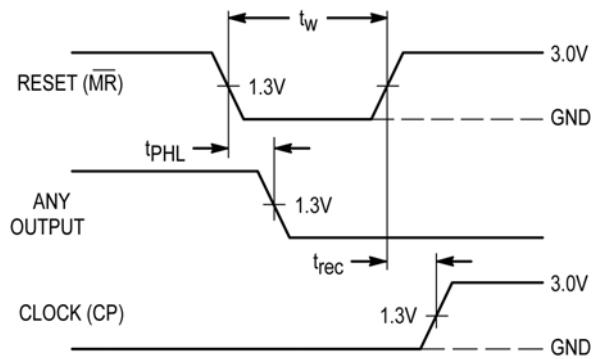


Figure 2 – Propagation Delay & Recovery Time, Reset to Clock



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Switching Waveforms continued

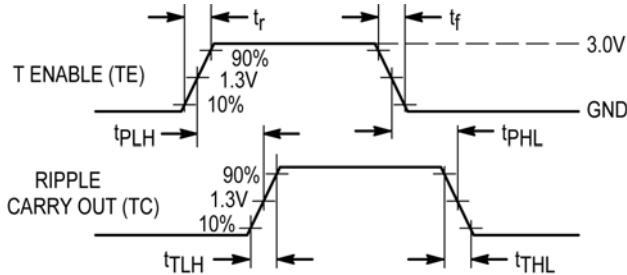


Figure 3 – Propagation Delay & Output Transition Time,
Enable to Ripple Carry

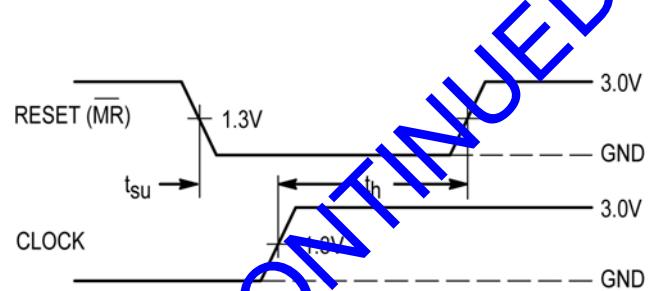


Figure 4 – Setup & Hold Timing,
Reset to Clock

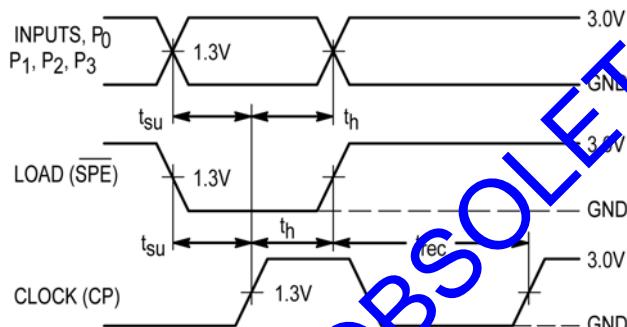


Figure 5 – Setup and Hold Timing,
Data to Clock

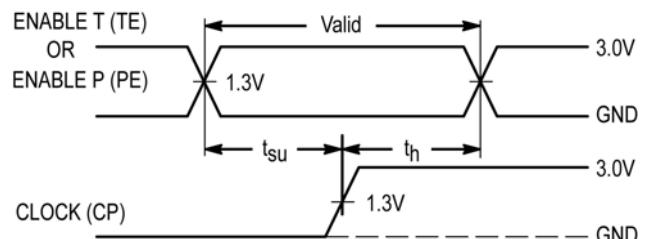


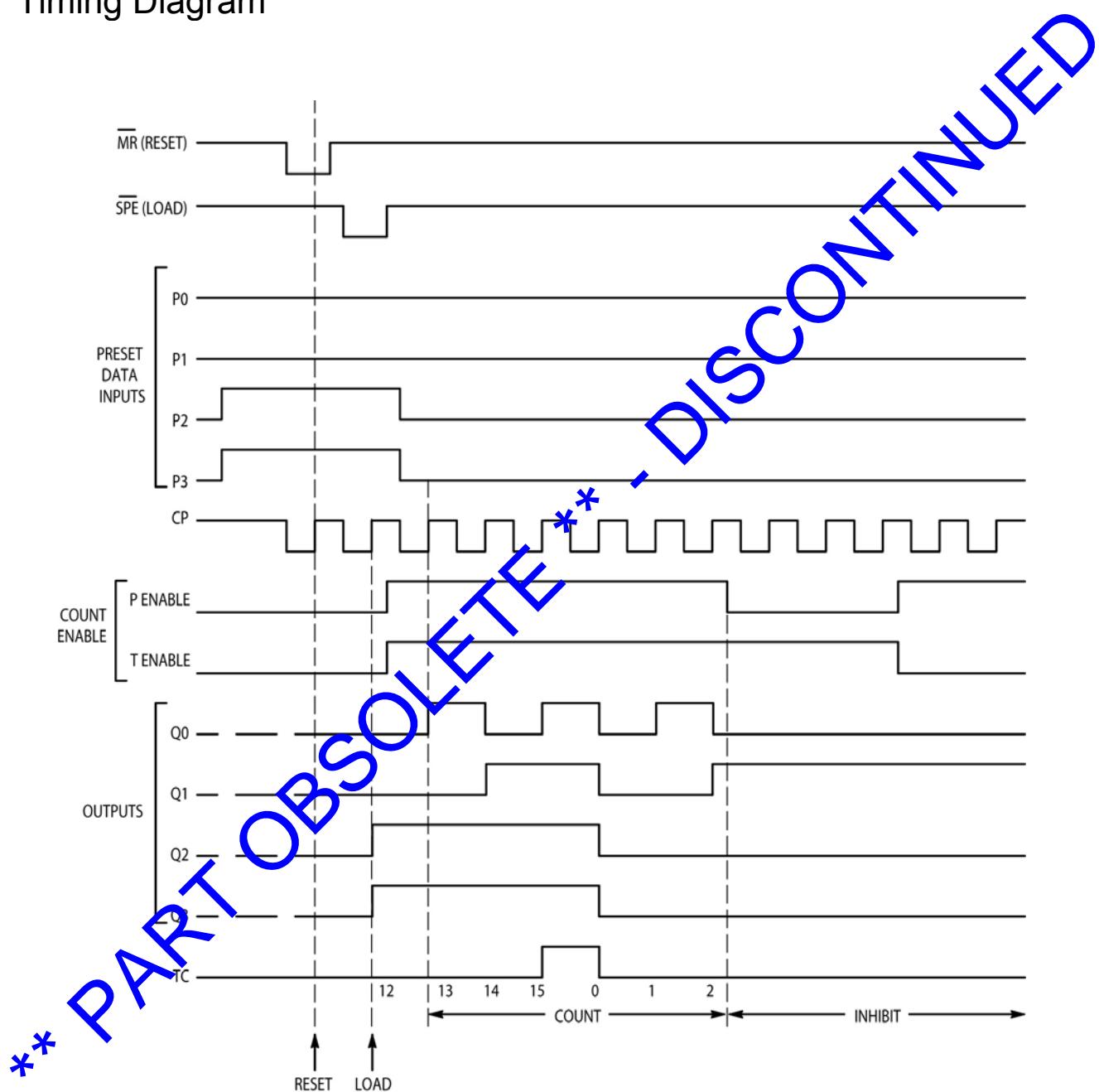
Figure 6 – Minimum Hold Time,
Enable to Clock



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Timing Diagram

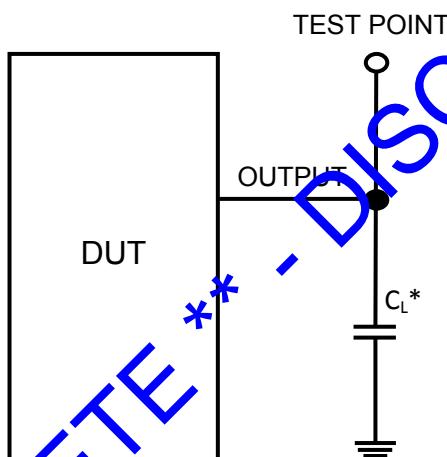




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Test Circuit



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